# antiplane shear of a domain with two closely located cracks* 

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#### Abstract

Antiplane deformation of a domain with two parallel cracks of different lengths, where the smaller can be above the larger or displaced relative to it, is investigated. A method of solving such problems was proposed in $/ 1 /$. The spacing between the cracks is considered to be a small parameter of the problem. An approximate solution (the deplanation asymptote) is constructed and, consequently, asymptotic formulas are sought for the stress intensity factors. Crack interaction was investigated numerically in $/ 2,3 /$.


1. Formulation of the problem. Let $\Omega$ be a domain in the plane $\mathbf{R}^{2}$ with a smooth (in the class $\mathbf{C}^{\infty}$ ) boundary $\partial \Omega$, containing the segment $N=\left\{x \leqslant \mathbf{R}^{2}: x_{0}=0,-1 \leqslant x_{1} \leqslant 1\right\}$. We
introduce still another segment dependent on the small positive para-


Fig. 1
meter $\varepsilon \quad M_{\varepsilon}=\left\{x: x_{2}=\varepsilon, \quad a \leqslant x_{1} \leqslant b\right\}$ and the domain $\Omega_{\varepsilon}=\Omega$ ( $N \cup M_{\varepsilon}$ )
(Fig.l). Here $a$ and $b$ are numbers in the interval ( $-1,1$ ); $\varepsilon \ll \min$ $\{1-b, 1+a, a+b\}$. We will examine the antiplane shear problem in the domain $\Omega_{\varepsilon}$

$$
\begin{align*}
& \mu \Delta u(\varepsilon, x)=0, \quad x \in \Omega_{\varepsilon} ; \quad \mu \frac{\partial u}{\partial n}(\varepsilon, x)=q(x), \quad x \in \partial \Omega  \tag{1.1}\\
& \mu \frac{\partial u}{\partial x_{2}}\left(\varepsilon, x_{1}, \varepsilon \pm 0\right)=\mp p^{\frac{ \pm}{M}}\left(x_{1}\right), \quad a<x_{1}<b \\
& \mu \frac{\partial u}{\partial x_{2}}\left(\varepsilon, x_{1}, \pm 0\right)=\mp p^{ \pm}\left(x_{1}\right), \quad-1<x_{1}<1
\end{align*}
$$

where $u$ is the deplanation, $\mu$ is the shear modulus, $n$ is the unit external normal vector to $\partial \Omega$, and $q$ and $p_{M^{ \pm}}, p_{N^{ \pm}}$are smooth external loads applied to the contour of $\partial \Omega$ and the edges $M_{\varepsilon}^{ \pm}, N \pm$ of the slits $M_{\varepsilon}, N$, respectively. We assume that the forces on the boundary of $\partial S_{F}$ are selfequilibrated, i.e, the following condition is satisfied:

$$
\begin{equation*}
\int_{\partial \Omega} q(x) d l+\sum_{ \pm}\left\{\int_{a}^{b} p^{\stackrel{\rightharpoonup}{M}}\left(x_{1}\right) d x_{1}+\int_{-1}^{1} p_{\bar{N}}^{+}\left(x_{1}\right) d x_{1}\right\}=0 \tag{1.2}
\end{equation*}
$$

for the solvability of the boundary value problem (1.1) in the space $W_{2}{ }^{1}\left(\Omega_{\varepsilon}\right)$ (or in the class of bounded functions).

Let $r_{b}, \theta_{b}$ be polar coordinates with centre at the vertex $(b, \varepsilon)$ of the crack $M_{\varepsilon}$ such that the edges $M_{e}^{ \pm}$are given by the relations $\theta_{b}= \pm \pi$. The representation

$$
\begin{equation*}
u(\varepsilon, x)=\mathrm{const}: K_{b}(\varepsilon) u^{-1}\left(1 / 2 r_{b} / \pi\right)^{1 / 2} \sin 1 / 2 \theta_{b}+0\left(r_{b}\left|\ln r_{b}\right|\right) \tag{1.3}
\end{equation*}
$$

holds for the solution $u$ of problem (1.1) in a small neighbourhood of the point ( $b, \varepsilon$ ) where $K_{b}(\varepsilon)$ is the stress intensity factor /4/. Analogous formulas also hold near the ends ( $a, \varepsilon$ ) and $(+1,0)$ of the slits $M_{e}$ and $N$. We denote the appropriate intensity factors by $K_{0}$ ( $\varepsilon$ ) and $K_{ \pm}(\varepsilon)$.

A method of solving this problem and a broader class of problems in ideal fluid flow is developed in /l/. It utilized conformal mapping and enables the problem to be reduced to an evaluation of quadratures. The purpose of this paper is to construct an asymptotic expansion in the parameter $\varepsilon$. Taking account of the smallness of $\varepsilon$, the asymptotic solution of problem (1.1) is expressed in terms of the solution of a simpler problem in the domain $\Omega$ with one slit $N$ (which can be solved, in turn, by using the method described in /1/). Approximate formulas for the intensity coefficients that clarify their qualitative dependence on the small spacing between the cracks are obtained as a result. In the case of canonical domains, when the limit problem has a solution in analytic form, the relationships obtained acquire an especially explicit form.
2. Asymptotic form of the solution in a narrow strip between cracks. we consider (1.1) and the boumdary conditions (1.3), (1.4) as a boundary value problem in a thin domain $\Pi_{\varepsilon}=\left\{x: 0<x_{2}<\varepsilon, a<x_{1}<b\right\}$. Following /5-7/, we will seek the asymptotic expression of the function $u$ in the form of the sum

$$
\begin{equation*}
u(\varepsilon, x) \sim \varepsilon^{-1} u_{0}\left(x_{1}\right)+u_{1}\left(x_{1}\right)+\varepsilon W_{0}\left(x_{1}, \varepsilon^{-1} x_{2}\right) \equiv W(\varepsilon, x) \tag{2,1}
\end{equation*}
$$

Substituting (2.1) into the equation and the last two conditions in (1.1) and equating coefficients of $\varepsilon^{-1}$ and $\varepsilon_{0}$, we obtain the relationships

$$
\begin{align*}
& \mu \frac{\hat{\partial}^{2} \Gamma_{n}^{n}}{\partial \eta^{2}}\left(x_{1}, \eta\right)+\mu \frac{d^{2} \mu_{n}}{d x_{1}{ }^{2}}\left(x_{1}\right)=0, \quad \eta \in(0,1)  \tag{2.2}\\
& \mu \frac{\partial F_{n}}{\partial \eta}\left(x_{1}, 1\right)=p_{M}^{-}\left(x_{1}\right), \quad \mu \frac{\partial F_{11}}{\partial \eta}\left(x_{1}, 0\right)=-p_{N}^{+}\left(x_{1}\right) ; \quad \eta=\frac{x_{2}}{r}
\end{align*}
$$

If (2.2) is considered as a boundary value problem in the function $W_{0}$ (with the parameter $\left.x_{1}=(a, b)\right)$, then the equation

$$
\begin{equation*}
\mu \frac{d^{2} w_{n}}{d x_{1}{ }^{2}}\left(x_{1}\right)=\cdots p_{M}^{-}\left(x_{1}\right)-p_{\mathrm{N}}^{+}\left(x_{1}\right), \quad x_{1} \in(a, b) \tag{2.3}
\end{equation*}
$$

which must be considered as an equation for the unknown function $u_{0}$, is the condition for its solvability. The necessary boundary conditions for (2.3) will be determined in Sect. 5 when studying boundary layers near the points $(a, \varepsilon)$ and $(b, \varepsilon)$.

The equation for the function $w_{1}$ in (2.1) has the same form as (2.3), and is found by using the same reasoning (see Sect. 5 of $/ 7 /$, say). However, the function $w_{1}$ is not needed to construct the princlpal term of the asymptotic expression of $u$. We merely note that the equation mentioned has a zero right-hand side, i.e., $w_{1}$ is a linear function.
3. The asymptotic form of the solution far from $\Pi_{\varepsilon}$. If we set $\varepsilon=0$, then the domain $\Omega_{\varepsilon}$ is transformed into the domain $\Omega_{0}$ with a single crack $N$. The boundary value problem (1.1) hance transforms into the following

$$
\begin{align*}
& \mu \Delta v_{0}(x)=0, \quad x=Q_{0} ; \quad \mu \frac{\partial x_{0}}{\partial n}(x)=q(x), \quad x \cong \partial \varrho  \tag{3.1}\\
& \because \frac{\partial c_{0}}{\partial x_{2}}\left(x_{1}, \therefore 0\right)=-p_{\mathrm{N}}^{+}\left(x_{1}\right), \quad x_{1} \equiv(1, a) \cup(b, 1) \\
& \mu \frac{\partial x_{1}}{\partial x_{2}}\left(x_{1},+0\right)=-p_{M}^{+}\left(x_{1}\right), \quad x_{1} \equiv(a, b) ; \\
& \mu \frac{\partial c_{n}}{\partial x_{1}}\left(x_{1},-0\right)=p_{\mathrm{N}}^{-}\left(x_{1}\right), \quad x_{1} \in(-1,1)
\end{align*}
$$

Problem (3.1) cannot have a bounded solution since by virtue of (1.2)

$$
\begin{equation*}
\mu_{\partial z_{0}} \int_{\partial s_{0}} \frac{\partial r_{0}}{\partial n_{n}}(x) d s=-I, \quad I=\int^{3}\left(p_{N}^{+}\left(x_{1}\right)+p_{M}^{-}\left(x_{1}\right)\right) d x_{1} \tag{3.2}
\end{equation*}
$$

Consequently, it is necessary to expand the class of functions allowable as solutions. Namely, we extract the points $(a,+0)$ and $(b,+0)$ that are images of the tips of the crack $M_{\mathcal{\varepsilon}}$, and we permit the functions $u$ to have logarithmic singularities at these points. Then the boundary value problem becomes solvable; however, its solution will be determined to the accuracy of a linear combination of two functions satisfying the homogeneous problem. The first is identically equal to one, while the second agrees with the Neumann function $G$ whose poles are at the points $(a,+0)$ and $(b,+0)$. We recall that the function $G$ satisfies the relationships

$$
\begin{gather*}
\Delta G(x)=0, \quad x \in \Omega_{0} ; \quad \frac{\partial G}{\partial n}(x)=0, \quad x=\partial \varrho_{0}  \tag{3.3}\\
G(x)=-\pi^{-1} \ln r_{b}+G_{b}+O\left(r_{b}\right), x_{2}>0, r_{b} \rightarrow 0  \tag{3.4}\\
G(x)==\pi^{-1} \ln r_{a}+G_{a}+O\left(r_{a}\right), x_{2}>0, r_{a} \rightarrow 0 \tag{3.5}
\end{gather*}
$$

where $G_{a}$ and $G_{b}$ are certain constants.
Thus, we select the linear combination

$$
\begin{equation*}
u(\varepsilon, x) \sim c_{v}+V_{0}(x)+A_{0}(\varepsilon) G(x) \equiv V(\varepsilon, x) \tag{3.6}
\end{equation*}
$$

as the asymptotic expression of the function $u$ (as a solution of problem (3.1)), where $c_{v}$ is an arbitrary constant (rigid displacement), the quantity $A_{0}(\varepsilon)$ is to be determined, and $V_{0}$ is a function bounded outside any neighbourhood of the point ( $b, 0$ ) and satisfying (3.1) and subject to the relationship

$$
\begin{equation*}
V_{0}(x)-\pi^{-1} \mu^{-1} \ln r_{b} \because V_{t}+O\left(r_{b}\left|\ln r_{b}\right|\right), \quad x_{2}>0, \quad r_{b}-0 \tag{3.7}
\end{equation*}
$$

4. Boundary layers near the tips of the crack $M_{\varepsilon}$. A formal asymptotic expression of the functions $u$ inside and outside $\Pi_{\varepsilon}$ was found in sects. 2 and 3 . In order to combine these representations, and therefore, eliminate the arbitrariness in the selection of certain constants, we will study the behaviour of the solution of problem (1.1) in the neighbourhoods of the points $(a, \varepsilon)$ and $(b, \varepsilon)$. As usual, a boundary layer originates in these zones. By virtue of the symmetry of the problem, it is sufficient to consider just one tip of the crack $M_{\varepsilon}$, the point $(b, \varepsilon)$, to be specific. We make the change of coordinates $x \rightarrow \xi=\varepsilon^{-1}\left(x_{1}-b\right.$, $x_{2}$ ) a stretching of the domain $\Omega_{\varepsilon} \varepsilon^{-1}$ times relative to the point mentioned. Transferring to $\varepsilon=0$ and confining ourselves to a consideration of the equations for $\xi_{2} \geqslant 0$, we obtain the boundary value problem

$$
\begin{equation*}
\mu \Delta z(\xi)=0, \quad \xi \in \Xi ; \quad \mu \frac{\partial z}{\partial \xi_{2}}(\xi)=0, \quad \xi \Leftarrow \partial \Xi \tag{4.1}
\end{equation*}
$$

where $\Xi=R_{+}^{2} \backslash\left\{\xi \in \mathbf{R}^{2}: \xi_{2}=1, \xi_{1}<0\right\}$ is the upper half-plane with a cutout ray (Fig. 2). The domain $\Xi$ has two "exists" at infinity: in the form of

the angle $\Xi_{+}$and the half-pole $E_{-}$. We will list the solutions of problem (4.1) that have not more than polynomial growth in $\Xi$ and allow the estimate $O\left(|\ln | \xi \|^{m}\right)$ in $\Xi_{+}$. One such solution $\varsigma_{0}$ is obvious: $\zeta_{0}(\xi)=1$. From the results of $/ 8,9 /$ it follows that every solution $\xi_{1}$ possessing the properties mentioned will allow of the representation

Fig. 2

$$
\begin{align*}
& \zeta_{1}(\xi)=c_{1} \xi_{1}+c_{2}+O\left(\exp \left(\pi \xi_{1}\right)\right) \quad \text { as } \quad \xi_{1} \rightarrow \quad \infty \quad \text { in } E_{-}  \tag{4.2}\\
& \zeta_{1}(\xi)=c_{3} \ln |\xi|+c_{4}+O\left(|\xi|^{-1}|\ln | \xi \|\right) \quad \text { as }|\xi| \rightarrow
\end{align*}
$$

where $c_{j}$ are certain constants. We substitute $\zeta_{1}$ and $\zeta_{0}$ into the Green's formula for the domain $\Xi_{R}=\left\{\xi \in \Xi:|\xi|<R\right.$ for $\xi \in \Xi_{+}$, and $\xi_{1}>-R$ for $\left.\xi \in \Xi_{-}\right\}$, where $R$ is a large positive number. We have

$$
\begin{align*}
0= & \int_{\Xi_{R}}\left(\xi_{1}(\xi) \Delta \zeta_{0}(\xi)-\zeta_{0}(\xi) \Delta_{01}(\xi)\right) d \xi=  \tag{4.3}\\
& \int_{\partial \xi_{R}}\left(\zeta_{1}(\xi) \frac{\partial^{c} 0}{\partial n}(\xi)-\zeta_{0}(\xi) \frac{\partial_{-1}}{\partial n}(\xi)\right) d l
\end{align*}
$$

where $d l$ is an element of the length of the arc. The integrand in the last integral of (4.3) differs from zero only for the integral $I_{+}$along the arc $\left\{\pi-\arcsin \left(R^{-1}\right)>\theta>0,|\xi|=R\right\}$ and for the integral $I_{-}$along the segment $\left\{\xi_{1}=-R, 0<\xi_{2}<1\right\}$. Using (4.2), we find that

$$
\begin{align*}
& I_{+}=-\int_{0}^{\pi-\arcsin \left(R^{-1}\right)}\left(c_{3}+O\left(R^{-1} \ln R\right)\right) d \theta=-\pi c_{3}+O\left(R^{-1} \ln R\right)  \tag{4.4}\\
& I_{-}=\int_{0}^{1}\left(c_{1}+O(\exp (-\pi R))\right) d d_{\mathbf{\varepsilon}}^{\kappa}-c_{1}+O(\operatorname{erp}(-\pi R))
\end{align*}
$$

Therefore, passing to the limit as $R \rightarrow \infty$ and taking account of (4.4), we derive the equation $c_{1}=\pi c_{3}$ from (4.3).

It only remains to note the following. If it is assumed that the solution $z$ of problem (4.1) has the asymptotic expression (4.2) for $c_{1}-c_{3}-0$, then it follows from Grecn's formula of the form (4.3) for $\zeta_{1}$ and $z$ that $c_{2}=c_{4}$. Moreover, the solution that vanishes at infinity and corresponds to zero constants $c_{j}$ in (4.2) possesses a finite Dirichlet integral, and therefore, is trivial.

Thus, all the linearly independent solutions sought for problem (4.1) that have the mentioned growth at infinity are exhausted by two: $\zeta_{0}$ and $\zeta_{1}$. The function $\zeta_{1}$ is determined by using conformal mapping of the half-planc into the domain $\Xi$ :

$$
\begin{equation*}
\eta_{1}+i \eta_{2} \rightarrow \xi_{1}+i \xi_{2}=\pi^{-1}\left(e^{-1}\left(\eta_{1}+i \eta_{2}\right)+\ln \left(\eta_{1}+i \eta_{2}\right)\right) \tag{4.5}
\end{equation*}
$$

Namely, if $\gamma: \xi_{1}+i \xi_{2} \ldots \eta_{1}+i \eta_{2}$ is a reciprocal function to (4.5), then $\zeta_{1}$ is given by the equation /10/

$$
\begin{equation*}
\zeta_{1}(\xi)=\ln \left|\gamma\left(\xi_{1} i \xi_{2}\right)\right| \tag{4.6}
\end{equation*}
$$

Direct calculations result in the following values of the constants $c_{j}$ in the asymptotic forms (4.2) of the function (4.6)

$$
\begin{equation*}
c_{1}=\pi, c_{2}=0, c_{3}=1, c_{1}=1+\|_{\mathrm{n}} \pi \tag{4.7}
\end{equation*}
$$

Later a representation of the type (1.3) is needed for the function $\zeta_{1}$ near the tips of the slit

$$
\begin{equation*}
\zeta_{1}(\xi)=1+(2 \pi \rho)^{1 / 2} \sin ^{1 / 2} \varphi+O(\rho) \tag{4.8}
\end{equation*}
$$

where $\rho, \varphi$ are polar coordinates with centre $(0,1)$ such that the slit edges are given by the relations $q= \pm \pi$; here $\varphi=\theta+O(\varepsilon), \rho=\varepsilon^{-1}(r+O(\varepsilon))$ (see (1.3)).

Ne note finally that by allowing a linear growth of the function $z$ in the corner $E_{+}$we obtain one more solution $\xi_{2}(\xi)=\xi_{1}$ of the homogeneous boundary value problem (4.1) in addition to $\xi_{0}$ and $b_{1}$.
5. Combining asymptotic forms using boundary layers. We will seek an approximation of the solution $u$ of problem (1.1) in small neighbourhoods of the points ( $a, \varepsilon$ ) and $(b, \varepsilon)$ in the form

$$
\begin{align*}
& u(\varepsilon, x) \sim c_{a}(\varepsilon) \div B_{a}(\varepsilon) \zeta_{1}\left(\varepsilon^{-1}\left(a-x_{1}\right), \varepsilon^{-1} x_{2}\right) \equiv Z_{a}(\varepsilon, x)  \tag{5.1}\\
& u(\varepsilon, x) \sim c_{b}(\varepsilon) \div B_{b}(\varepsilon) \zeta_{1}\left(\varepsilon^{-1}\left(x_{1}-b\right), \varepsilon^{-1} x_{2}\right) \equiv Z_{b}(\varepsilon, x) \tag{5.2}
\end{align*}
$$

As mentioned earlier, the role of the boundary layers (5.1) and (5.2) is to combine the approximations to $u$. Using the method of combinable asymptotic expansions (/11-13/, etc.), we find the quantities $c_{a}(\varepsilon), c_{b}(\varepsilon), B_{a}(\varepsilon), B_{b}(\varepsilon)$ and $A_{0}(\varepsilon)$ in (5.1), (5.2) and (3.6) from the condition that the asymptotic expansions (2.1) and (3.6) should be in agreement in common intermediate zones.

If the point $x$ is such that $0<x_{2}<\varepsilon, x_{1} \sim b-\sqrt{\varepsilon}$, then

$$
W(\varepsilon, x)=\varepsilon^{-1} u_{0}(0)+w_{1}(0)+\frac{x_{1}-b}{\varepsilon} \frac{d w_{0}}{d x_{1}}(b)+\frac{\left(x_{1}-b\right)^{2}}{2 \varepsilon} \frac{a^{2} u_{0}}{d x_{1}^{2}}(b)+O(\sqrt{\varepsilon})
$$

or in $\xi$ coordinates (see sect. 4)

$$
\begin{align*}
& W(\varepsilon,(b, 0)+\varepsilon \bar{E})=\varepsilon^{-1} u_{0}(0)+u_{1}(0)+\xi_{1} \frac{d w_{0}}{d x_{1}}(b)+  \tag{5.3}\\
& \quad \frac{r \varepsilon_{1}^{2}}{2} \frac{a^{2} w_{0}}{d x_{1}^{2}}(b)+O(\overline{\gamma \varepsilon})
\end{align*}
$$

Using (4.2) and (4.7), we find that

$$
\begin{equation*}
Z_{b}(\varepsilon, x)-c_{b}(\varepsilon)+B_{b}(\varepsilon) \pi \xi_{1}+O\left(\exp \left(\pi \xi_{1}\right)\right) \tag{5.4}
\end{equation*}
$$

Equating (5.3) and (5.4), we deduce the relations

$$
\begin{equation*}
c_{b}(\varepsilon)=e^{-1} u_{0}(0) \div u_{1}(0), \quad B_{b}(\varepsilon) \equiv B_{b}=\pi^{-1} \frac{d w_{n}}{\partial x_{1}}(b) \tag{5.5}
\end{equation*}
$$

If $x_{2}>\varepsilon$ and $r_{b} \sim \sqrt{\varepsilon}$, then according to (3.4)-(3.7) we have

$$
\begin{equation*}
V(\varepsilon, x)=r_{v}+\pi^{-1} / \mu^{-1} \ln r_{b}-\vdots V_{b}{ }^{\theta}+A_{0}(\varepsilon)\left(-\pi^{-1} \ln r_{b}+G_{b}\right)+0(\sqrt{\varepsilon}) \tag{5.6}
\end{equation*}
$$

Moreover, in the same zone the formula

$$
\begin{equation*}
Z_{b}(\varepsilon, x)=\epsilon_{b}(\varepsilon)+B_{b}\left(\ln \left(r_{\varepsilon} \varepsilon^{-1}\right)+\ln \pi+1\right)+O(/ / \varepsilon) \tag{5.7}
\end{equation*}
$$

follows from (4.2) and (4.7).
The relations

$$
\begin{equation*}
\mu^{-1} I-A_{0}(\varepsilon)=\pi B_{b}, \quad c_{v}+V_{b}^{0}+A_{0}(\varepsilon) G_{b}=c_{b}(\varepsilon)+B_{b}\left(\ln \left(\varepsilon^{-1} \pi\right)+1\right) \tag{5.8}
\end{equation*}
$$

result from the assumption about the coincidence of the asymptotic expressions (5.6) and (5.7).
In considering the boundary layer $Z_{a}$ the relationships

$$
\begin{align*}
& \varepsilon_{a}(\varepsilon)=\varepsilon^{-1} u_{0}(a)+u_{1}(a), \quad B_{0}(\varepsilon)=B_{a}=-\pi^{-1} \frac{d w_{0}}{d x_{1}}(a)  \tag{5.9}\\
& A_{0}(\varepsilon)=\pi B_{0} ; \quad c_{v}+V_{a}^{\theta}+A_{0}(\varepsilon) G_{a}=c_{a}(\varepsilon)+B_{a}\left(\ln \left(\varepsilon^{-1} \pi\right)+1\right)
\end{align*}
$$

are deduced in exactly the same way.
Solving the system of algebraic Eqs. (5.5), (5.8), (5.9), we find the missing boundary conditions for the function $u_{0}$ satisfying (2.3)

$$
\begin{equation*}
u_{0}(b)-u_{0}(a)=0, \quad \frac{d w_{0}}{d x_{1}}(b)-\frac{d u_{0}}{d x_{1}}(a)=I \mu^{-1} \tag{5.10}
\end{equation*}
$$

the expressions for the unknown constant

$$
\begin{equation*}
A_{0}(r)=A_{0}=-\frac{1}{\pi} \frac{d w_{0}}{d x_{1}}(a), \quad R_{a}=-\frac{1}{\pi} \frac{d w_{0}}{d x_{1}}(a), \quad B_{b}=-\frac{1}{\pi} \frac{d w_{0}}{d x_{1}}(b) \tag{5.11}
\end{equation*}
$$

and also one of the boundary conditions for the function $w_{1}$

$$
\begin{gathered}
w_{1}(b)-w_{1}(a)=V_{b}^{0}-V_{a}^{0}-\frac{1}{\pi} \frac{d w_{0}}{d x_{1}}(a)\left(G_{b}-G_{a}\right)+ \\
\frac{1}{\pi}\left(1+\ln \frac{\pi}{\varepsilon}\right)\left(\frac{d w_{0}}{d x_{1}}(b)+\frac{d w_{0}}{d x_{1}}(a)\right)
\end{gathered}
$$

The second boundary condition and, as remarked earlier, the equation for $w_{1}$ are determined when constructing the next terms of the asymptotic forms.

We note that problem (2.3), (5.10) is solvable (according to the definition (3.2) of the quantity $I$ and the assumption (1.2) about the selfequilibration of the load).
6. Foundation for the asymptotic expansion. We assume the solutions $u$, $V$ and $G$ of problems (1.1), (3.1), (3.7) and (3.3)-(3.5) are normalized by the conditions

$$
\begin{equation*}
\int_{\partial \Omega} u(e, x) d x=\int_{\partial \Omega} V(\varepsilon, x) d x=\int_{\partial \Omega} G(x) d x=0 \tag{6.1}
\end{equation*}
$$

Let $\chi$ be the cutoff function from $\mathbf{C}_{0}^{\infty}\left(\mathbf{R}^{1}\right)$ such that $\chi(t)=0$ for $|t| \geqslant 1$ and $\gamma(t)=1$ for $|t|<\frac{1 / 2}{}$ while $\chi(\varepsilon, x)=\left(1-\chi\left(r_{a} \varepsilon^{-1 / x}\right)\right)\left(1-\chi\left(r_{b} \varepsilon^{-1 / 2}\right)\right)$. We introduce the function

$$
\begin{align*}
& U(\varepsilon, x)=V(\varepsilon, x), \quad x \in \Omega_{\varepsilon}, \quad x_{2}<0  \tag{6.2}\\
& U(\varepsilon, x)=\chi(\varepsilon, x) V(\varepsilon, x)+\chi\left(r_{a} \varepsilon^{-1 / 2}\right) Z_{a}(\varepsilon, x)+ \\
& \quad \chi\left(r_{b} \varepsilon^{-1 / 2}\right) Z_{b}(\varepsilon, x), \quad x \in \Omega_{\varepsilon} \backslash \bar{\Pi}_{\varepsilon}, \quad x_{2}>0 \\
& U(\varepsilon, x)=\left(1-\chi\left(\left(x_{1}-a\right) \varepsilon^{-1 / 2}\right)\left(1-\chi\left(\left(x_{1}-b\right) \varepsilon^{-1 / 2} W(\varepsilon, x)+\right.\right.\right. \\
& \quad \chi\left(\left(x_{1}-a\right) \varepsilon^{-1 / 2}\right) Z_{a}(\varepsilon, x)+\chi\left(\left(x_{1}-b\right) \varepsilon^{-1 / 2}\right) Z_{b}(\varepsilon, x), \quad x \cong \Pi_{\varepsilon}
\end{align*}
$$

(see (2.1), (3.6), (5.1), (5.2)). It is clear that $U$ satisfies the boundary conditions from (1.1) on $N, M_{e}^{-}$and $\partial \Omega$ but leaves a residual $\Phi\left(\varepsilon, x_{1}\right)$ on $M_{\varepsilon}^{+}$which allows of the estimate

$$
\begin{equation*}
\left|\Phi\left(\varepsilon, x_{1}\right)\right| \leqslant c_{1} \varepsilon\left[\left(x_{1}-a+\varepsilon\right)\left(b-x_{1}+\varepsilon\right)\right]^{1 / 2} \tag{6.3}
\end{equation*}
$$

Since the functions $V_{u}, Z_{a}$ and $Z_{b}$ are harmonic, residual $\Psi(\varepsilon, x)$ of the approximation $U$
in (1.1) is concentrated in the union of $\Pi_{\varepsilon}$ and the $\sqrt{\varepsilon}$ neighbourhoods of the points $(b,+0)$ and $(a,+0)$. By virtue of the agreement of the asymptotic forms $V$ and $Z, W$ and $Z$ near these points, the following relations hold:

$$
\begin{align*}
& |\Psi(\varepsilon, x)| \leqslant c_{2}\left(r_{a}+\varepsilon\right)^{-1}, r_{a}<\sqrt{\varepsilon}, x \equiv \Pi_{\varepsilon}  \tag{6.4}\\
& |\Psi(\varepsilon, x)| \leqslant c_{3}\left(r_{b}+\varepsilon\right)^{-1}, r_{b}<\sqrt{\varepsilon}, x \equiv \Pi_{\varepsilon} \\
& |\Psi(\varepsilon, x)| \leqslant c_{1} \varepsilon\left(\varepsilon+\left(x_{1}-a\right)\left(b-x_{1}\right)\right)^{-1}, x \in \Pi_{\varepsilon}
\end{align*}
$$

The estimate

$$
\begin{align*}
& \int_{\Omega_{\varepsilon}}\left\{|\nabla u-\nabla U|^{2}+d^{2}|u-U|^{2}\right\} d x \leqslant c_{J}\left\{\int_{\Omega_{\varepsilon}} d^{-2} \Psi^{2} d x+\int_{M_{\varepsilon}^{+}} \Phi^{2} d x_{1}\right\}  \tag{6.5}\\
& d(x)=r_{a}^{-1}\left(\left|\ln r_{a}\right|-1\right)^{-1}+r_{b}^{-1}\left(\left|\ln r_{b}\right|+1\right)^{-1}
\end{align*}
$$

results (according to (6.1)) from the one-dimensional Hardy inequality and the PoincaréFriedrichs inequalities.

By virtue of (6.3) and (6.4), the integral over $\Omega_{\varepsilon}$ from the right side of (6.5) does not exceed $c_{6} \varepsilon|\ln |^{2}$ and the integral over $M_{\varepsilon}^{+}$does not exceed $c_{7} \varepsilon$. Hence

$$
\begin{equation*}
\left\|u-U ; W_{2}^{1}\left(\Omega_{\mathrm{F}}\right)\right\| \leqslant \varsigma \sqrt{\varepsilon}|\ln \varepsilon| \tag{6.6}
\end{equation*}
$$

To simplify the discussion we will confine oursevles here to the deduction of just a rough estimation of the closeness of the constructed approximation (6.2) to the solution of the problem (1.1). The inequality (6.6) can be refined by using the method in /14/. In particulax, the relationships

$$
\begin{align*}
& u(\varepsilon, x)=V(\varepsilon, x) \div O(\varepsilon|\ln \varepsilon|) \quad \text { in } \quad \Omega_{\varepsilon} \backslash \Pi_{\varepsilon} \backslash D_{\delta}  \tag{6.7}\\
& u(\varepsilon, x)=Z(\varepsilon, x)-, O(\varepsilon|\ln \varepsilon|) \quad \text { in } \quad D_{\varepsilon} ; D_{\delta}=\left\{x \equiv \Theta_{\varepsilon}: \min \left\{r_{a}, r_{b}\right\}<\delta\right\}
\end{align*}
$$

hold, where $\delta$ is a fixed positive number. We note that the operator min $\left\{\varepsilon, r_{a}, r_{b}\right\}$ oforj can be applied to the left-hand sides of (6.7) without degrading the estimate of the residue.
7. Asymptotic expression for the intensity factors. Asymptotic formulas for the stress intensity factors at the tips of the cxacks $M_{\varepsilon}$ and $N$ are a result of the representations (6.7) of problem (1.1) (see (1.3)). We introduce the coefficients $k_{V} \pm$ and $k_{G} \pm$ into the expansions

$$
\begin{gather*}
V_{0}(x)=\text { const }_{ \pm}+\mu^{-1} k_{V}^{ \pm}\left(1 / 2 \frac{r_{ \pm}}{\pi}\right)^{1 / 2} \sin ^{1 / 2} \theta_{ \pm}+O\left(r_{ \pm}\left|\ln r_{ \pm}\right|\right)  \tag{7.1}\\
G(x)=\text { const } \pm+\mu^{-1} k_{G}^{ \pm}\left(1 / 2 \frac{r_{ \pm}}{\pi}\right)^{1 / 2} \sin ^{1} / 2 \theta_{ \pm} \because O\left(r_{ \pm}\right) \quad \text { as } \quad r_{ \pm} \rightarrow 0 \tag{7.2}
\end{gather*}
$$

of the harmonic functions $V_{0}$ and $G$ (see (3.7) and (3.3)-(3.5)). Here $r_{ \pm}, \theta_{ \pm}$are polar coordinates with centres $( \pm 1,0)$ such that the edges $N^{ \pm}$ot the slit $N$ are given by the equations $\theta_{ \pm}=\pi$ and $\theta_{ \pm}=-\pi$.

Comparing formulas (1.3), (3.6), (7.1), (7.2) and (5.11), we find that

$$
\begin{equation*}
K_{ \pm}(\varepsilon)=k_{V}^{ \pm}-\pi^{-1} \frac{d w_{0}}{d x_{1}}(a) k_{G}^{ \pm}+O(\varepsilon|\ln \varepsilon|) \tag{7.3}
\end{equation*}
$$

Similarly we deduce the following relationships from (5.1), (5.2) and (4.8)

$$
\begin{align*}
& K_{a}(\varepsilon)=2 \mu \varepsilon^{-1 / s} \frac{d w_{0}}{d x_{1}}(a)+O(\sqrt{\varepsilon}|\ln \varepsilon|)  \tag{7.4}\\
& K_{b}(\varepsilon)=-2 \mu \varepsilon^{-1 / 2} \frac{d w_{0}}{d x_{1}}(b)+O(\sqrt{\varepsilon}|\ln \varepsilon|)
\end{align*}
$$

The solution $w_{0}$ of the oridinary differential Eqs (2.3), (5.10) is contained in the asymptotic formulas (7.3), (7.4). If $w_{0}=$ const, then the representations (7.4) become of little interest. The latter holds, say, if the crack edges are stress-free, i.e., $p_{M^{ \pm}}=p_{N} \pm=$ 0 in (1.1). We consider the situation mentioned by constructing the second term of the asymptotic form (its proof is carried out exactly as in Sect. 6 and is omitted here). Far from $\Pi_{\varepsilon}$ we seek the asymptotic form $u$ in the form

$$
\begin{equation*}
u(\varepsilon, x) \sim v_{0}(x)+\varepsilon v_{1}(x)+\varepsilon A_{1} G(x) \tag{7.5}
\end{equation*}
$$

where $A_{1}$ is a certain constant and the function $v_{0}$ satisfies relationship (3.1) and the boundary condition

$$
\begin{equation*}
\mu \frac{\partial v_{0}}{\partial x_{2}}(x)=0, \quad x \fallingdotseq N^{ \pm} \tag{7.6}
\end{equation*}
$$

$v_{1}$ is the solution of the boundary value problem

$$
\begin{align*}
& \Delta v_{1}(x)=0, \quad x \in \Omega_{0} ; \quad \frac{\partial v_{1}}{\partial n}(x)=0, \quad x \equiv \partial \Omega  \tag{7.7}\\
& \frac{\partial v_{1}}{\partial x_{2}}\left(x_{1},+0\right)=\frac{\hat{\partial}^{2} v_{0}}{\partial x_{1}^{2}}\left(x_{1},+0\right), \quad x_{\mathbf{1}} \equiv(a, b)  \tag{7.8}\\
& \frac{\partial c_{1}}{\partial x_{2}}(x)=0, \quad x \models N^{-} \cup\left(N^{+} \backslash M_{0}{ }^{+}\right)
\end{align*}
$$

Let us clarify the reasons for this choice of the right-hand sides of the boundary conditions (7.8). Expanding the function on the right in (7.5) in a Maclauren series, we find that for $x \in M_{\varepsilon}^{+}$(or $x_{1} \in(a, b), x_{2}=\varepsilon+0$ )

$$
\begin{align*}
& \frac{\partial u}{\partial x_{3}}\left(\varepsilon, x_{1}, \varepsilon+0\right) \sim \frac{\partial c_{0}}{\partial x_{2}}\left(x_{1},+0\right)+\varepsilon\left(\frac{\partial c_{1}}{\partial x_{2}}\left(x_{1},+0\right)+\frac{\partial}{+}\right.  \tag{7.9}\\
& \quad A_{1} \frac{\partial G}{\partial x_{2}}\left(x_{1},+0\right)+\frac{\tilde{a}^{2} c_{0}}{\partial x_{2}^{2}}\left(x_{1},+0\right)+O\left(\varepsilon^{2}\right)
\end{align*}
$$

Since $v_{0}$ and $G$ satisfy the homogeneous Neumann conditions on $N^{+}$, the coefficient of $\varepsilon$ from (7.9) vanishes if

$$
\frac{\partial_{c_{1}}}{\partial x_{2}}\left(x_{2},+U\right) \equiv-\frac{\partial^{2} v_{u}}{\partial x_{2}{ }^{2}}\left(x_{1}, \div 0\right)=\frac{\partial^{2} v_{0}}{\partial x_{1}{ }^{2}}\left(x_{1},+\cup\right)-\Delta c_{0}\left(x_{1}, \div 0\right)=\frac{\partial^{2} v_{0}}{\partial x_{1}{ }^{2}}\left(x_{1},+0\right)
$$

According to Sect.3, a solution of the problem (7.7), (7.8) exists that is bounded outside any neighbourhood of the point $(b,+0)$ and allows of the representation (compare with (3.8))

$$
\begin{gather*}
v_{1}(x)=\pi^{-1} I_{1} \ln r_{b}-i V_{b}^{1} \div O\left(r_{b}\left|\ln r_{b}\right|\right) \quad \text { as } \quad r_{b} \rightarrow 0, x_{2}>0  \tag{7.10}\\
I_{1}=-\int_{\partial L_{0}} \frac{\partial r_{1}}{\partial n}(x) d s=-\int_{u}^{b} \partial^{2} \frac{\partial^{2} r_{0}}{\partial x_{1}{ }^{2}}\left(x_{1},-0\right) d x_{1}=  \tag{7.11}\\
\frac{\partial c_{0}}{\partial x_{1}}(a,-0)-\frac{\partial c_{0}}{\partial x_{1}}(b, \div 0)
\end{gather*}
$$

Inside $\Pi_{8}$ the solution $u(\varepsilon, x)$ is approximated by the quantity $u_{1}\left(x_{1}\right)$ which is a linear function $\alpha x_{1}+\beta$ (see sect.2). The boundary layers (5.1) and (5.2) have the form

$$
\begin{align*}
& Z_{a}(\varepsilon, x)=c_{a}^{0}+\varepsilon\left(c_{a}^{x}+B_{a} \xi_{1}\left(\frac{a-x_{1}}{\varepsilon}, \frac{x_{2}}{\varepsilon}\right)+D_{a b_{2}}\left(\frac{a-x_{1}}{\varepsilon}, \frac{x_{2}}{\varepsilon}\right)\right)  \tag{7.12}\\
& Z_{b}(\varepsilon, x)=c_{b}^{\theta}+\varepsilon\left(c_{b}^{x}+B_{b} \zeta_{1}\left(\frac{x_{1}-b}{\varepsilon}, \frac{x_{2}}{\varepsilon}\right)+D_{b} b_{2}\left(\frac{x_{1}-b}{\varepsilon}, \frac{x_{2}}{\varepsilon}\right)\right) \tag{7.13}
\end{align*}
$$

Performing the combination, we obtain algebraic equations as in Sect. 5

$$
\begin{align*}
& \alpha b+\beta=v_{0}(b,+0), \alpha a+\beta=v_{0}(a,+0), \pi B_{b}=I_{1}-A_{1}  \tag{7.14}\\
& \pi B_{a}=A_{1}, \quad \alpha=\pi B_{b}+D_{b}=-\pi B_{a}-D_{a}, \quad D_{b}=\frac{\partial v_{0}}{\partial x_{1}}(b,+0), \\
& D_{a}=-\frac{\partial v_{n}}{\partial x_{1}}(a,+0)
\end{align*}
$$

Solving the overdefined but solvable system (7.14), by virtue of (7.11), we find that

$$
\begin{align*}
& A_{1}=\pi B_{a}=I_{1}-\pi B_{b}, \alpha=\left(v_{0}(b,+0)-v_{0}(a,+0)\right)(b-a)^{-1}  \tag{7.15}\\
& B_{b}=\frac{1}{\pi}\left(\alpha-\frac{\partial c_{n}}{\partial v_{1}}(b,+0)\right), \quad B_{a}=\frac{1}{\pi}\left(\frac{\partial c_{0}}{\partial c_{1}}(a,+0)-\alpha\right)
\end{align*}
$$

Therefore, the following asymptotic formulas for the intensity factors result from (7.5), (7.12), (7.13) and (7.15) in the solution of problem (1.1) for $p_{M^{ \pm}}^{ \pm}=p_{N^{ \pm}}=0$

$$
\begin{align*}
& K_{ \pm}(\varepsilon)=k_{v} \pm+\varepsilon\left\{k_{1, v}^{ \pm}+k_{G}^{ \pm}\left(\frac{\partial v_{0}}{\partial x_{1}}(a,+0)-\right.\right.  \tag{7.16}\\
& \left.\left.\frac{c_{n}\left(b_{1}+O_{1}-v_{0}\left(a_{,}+0_{j}\right)\right.}{b-a}\right)\right], O\left(\varepsilon^{2}|\ln \varepsilon|\right) \\
& K_{b}(\varepsilon)=2 \mu \sqrt{\varepsilon}\left\{\frac{v_{n}\left(b,+(1)-v_{0}\left(a_{4}+0\right)\right.}{b-a}-\frac{\partial r_{0}}{\partial x_{1}}(b, \cdots, 0)\right\}+O\left(\varepsilon^{s^{3}}|\ln \varepsilon|\right) \tag{7.17}
\end{align*}
$$

where $k_{1, v}^{ \pm}$are coefficients in representations of the type (7.1) and (7.2) for the solution $u_{i}$ of problem (7.7), (7.8). (We note that the asymptotic form $K_{" 1}(\varepsilon)$ has the form (7.17) where the opposite sign should be taken and $a$ and $b$ interchanged).

When $\Omega=\mathbf{R}^{2}$ formulas (7.16) and (7.17) take a more specific form. In particular, for functions $u$ harmonic in $\Omega_{\varepsilon}=\mathbf{R}^{*} \backslash\left(Y \cup M_{e}\right)$ and subject to the relations

$$
\begin{align*}
& \mu \frac{\partial u}{\partial n}(\varepsilon, x)=0, \quad x \in N \cup M_{\varepsilon} ;  \tag{7.18}\\
& \mu \frac{\partial u}{\partial x_{\mu}}(\varepsilon, x)=q_{0}+o(1) \quad \text { as } \quad|x| \rightarrow+\infty
\end{align*}
$$

the intensity factors are calculated from the formulas

$$
\begin{align*}
& K_{+}(\varepsilon)=2 q_{0} \sqrt{\pi}\left\{1+\frac{\varepsilon}{2 \pi}\left[\frac{1}{4} \ln \frac{(1+b)(1-a)}{(1+a)(1-b)}+\right.\right.  \tag{7.19}\\
& \frac{1}{2} \frac{b-a}{(1-a)(1-b)}+\sqrt{1+b}\left(\frac{b}{\sqrt{1-b^{2}}}-\frac{a}{\sqrt{1-a^{2}}}\right)+ \\
& \left(1 \frac{1+b}{1-b}-\sqrt{\frac{1+a}{1-a}}\right)\left(\frac{a+b}{\sqrt{1-a^{2}+\sqrt{1-b^{2}}}}-\right. \\
& \left.\left.\left.\frac{a}{\sqrt{1-a^{2}}}\right)\right]\right\}-O\left(\varepsilon^{2}|\ln \varepsilon|\right) \\
& K_{b}(\varepsilon)=2 g_{0} \sqrt{\varepsilon} \frac{1}{\sqrt{1-b^{2}}} \frac{b-a}{1-a b+\sqrt{\left.1-a^{2}\right)\left(1-b^{2}\right)}}+O\left(\varepsilon^{\%} / 2|\ln \varepsilon|\right)
\end{align*}
$$

8. Cracks shifted relative to one another. We will investigate a crack arrangement different from that studied in Sects.1-7. We retain the same notation as in Sect.l for $a, b, \varepsilon$ and $\Omega$. We set $M_{e}=\left\{x \in \mathbf{R}^{2}: x_{2}=\varepsilon,-1 \leqslant x_{1} \leqslant b\right\}, \quad N_{1}=\left\{x \in \mathbf{R}^{2}: x_{2}=0, a \leqslant x_{1} \leqslant 1\right\}, \Omega_{s}-\Omega \backslash$ $N_{1} \backslash M_{\varepsilon}$ (Fig.3). We consider (1.1) with zero Neumann data on $N_{1} \cup M_{\varepsilon}$. The asymptotic form of the solution is constructed by the same scheme as before. The sole difference is in the definition of the function $v_{1}$.

In the case under consideration the residual $\partial^{2} v_{0} / \partial x_{1}{ }^{2}$ occurs in the set $M_{e}{ }^{+} \cup\left\{x \subseteq M_{\varepsilon}{ }^{\text {n }}\right.$; $\left.-1 \leqslant x_{1} \leqslant a\right\}$, and consequently, the right-hand sides of the boundary conditions of the type (7.8) have the inadmissible growth $O\left(r_{-}^{-3 / 2}\right)$ as $r_{-} \rightarrow 0$. The reason for such growth is that the image ( $-1,0$ ) of the left tip of the crack $M_{8}$ in the limit problem is shifted relative to the initial position and the function $v_{0}$ does not satisfy the boundary conditions near $(-1,0)$. Consequently, it is necessary to change the form of the fundamental approximation to $u$ by
selecting

$$
\begin{align*}
& \nu^{*}(\varepsilon, x)=\mathrm{X}_{\delta}(x) v_{0}\left(x_{1}, x_{2}+\varepsilon\right)+\left(1-\mathrm{X}_{\delta}(x)\right) v_{0}(x)  \tag{8.1}\\
& \mathrm{X}_{\delta}(x)=\chi\left(\delta^{-1}\left(x_{1}+1\right)\right) \chi\left(\delta^{-1} x_{2}\right)
\end{align*}
$$

as its function, where $\%$ is the cutoff from Sect. 6 , and $\delta$ is so small a number that the support $X_{\delta}$ intersects neither $\partial \Omega$ nor $N_{1}$. We note that outside the neighbourhood of the point $(-1, \varepsilon)$ the function (8.1) is expanded in a series of non-negative integer powers of $\varepsilon$; this expansion is obtained after application of Taylor's formula to the first term on the right in (8.1).


Fig. 3


Fig. 4

The principal term of the residual $v^{*}$ in the boundary condition (1.1) has the form erpit, where

$$
\begin{aligned}
& \mathbb{T}^{+}\left(x_{1}\right)=\chi\left(\delta^{-1}\left(x_{1}+1\right)\right) \frac{\partial^{2} v_{0}}{\partial x_{1}^{2}}\left(x_{1},+0\right), \quad x_{1}=(-1, b) \\
& \Psi_{1}^{+}\left(x_{1}\right)=0, \quad x_{1}=(b, 1) ; \quad \varphi_{1}^{-}\left(x_{1}\right)=0, \quad x_{1} \in(a, 1) \\
& \mathbb{T}_{1}^{-}\left(x_{1}\right)=\chi\left(\delta^{-1}\left(x_{1}+1\right)\right) \frac{\partial^{2} x_{0}}{\partial x_{1}^{2}}\left(x_{1},-0\right), \quad x_{1} \leqslant(-1, a)
\end{aligned}
$$

Moreover, a residual appears in (1.1) whose principal term agrees with the quantity $\varepsilon \mu \psi_{2}(x)$, where

$$
\psi_{1}(x)=-\frac{\partial \hat{D}_{n}}{\partial x_{2}}(x) \Delta \mathrm{X}_{\delta}(x)-2 \nabla \frac{\partial \sigma_{\mathrm{B}}}{\partial x_{\delta}}(x) \cdot \nabla \mathrm{X}_{\delta}(x)
$$

Since $v_{0}$ is a harmonic function, then

$$
\begin{aligned}
& \int_{\Omega_{0}} W_{1}(x) d x=\int_{\Omega_{0}}\left(\frac{\partial X_{0}}{\partial x_{3}}(x) \frac{\partial^{2} x_{0}}{\partial x_{1}{ }^{2}}(x)-\frac{\partial \mathrm{X}_{0}}{\partial x_{\mathrm{a}}}(x) \frac{\partial^{2} x_{0}}{\partial x_{1} \partial x_{2}}(x)\right) d x= \\
& \quad \sum_{ \pm}^{\Gamma} \mp \int_{-1}^{a} \frac{\partial \gamma}{\partial x_{1}}\left(\delta^{-1}\left(x_{1}+1\right)\right) \frac{\partial v_{0}}{\partial x_{1}}\left(x_{1}, \pm 0\right) d x_{1}
\end{aligned}
$$

and consequently, a solution $v_{1}$ of the boundary value problem exists

$$
\begin{align*}
& \Delta v_{1}(x)=\psi_{1}(x), x \in \Omega_{0}  \tag{8.2}\\
& \frac{\partial v_{2}}{\partial x_{2}}(x)= \pm \varphi_{1} \pm\left(x_{1}\right), \quad x \in N \pm ; \quad \frac{\partial c_{2}}{\partial n}(x)=0, \quad x \in \partial Q
\end{align*}
$$

which allows of the representation (7.10), (7.11), where ( $a,+0$ ) should be replaced by ( $a,-0$ ).
The remaining reasoning for the construction of the asymptotic expression is exactly the same as in sect.7. We consequently obtain the asymptotic formulas (7.16), (7.17) for the intensity factors, in which $(a,+0)$ must be replaced by $(a,-0)$ and $l_{1,}^{+}$, should be understood to be the factors in the asymptotic forms of the solution of problem ( 8.2 ), while $k_{G^{ \pm}}$ are the factors in the expansion (7.2) of the Neumann functions with poles ( $a,-0$ ) and (b. +0 ) (compare with (3.4) and (3.5)). In the case of problem (1.1). (7.18) in a plane, formulas (7.19) become

$$
\begin{aligned}
& K_{+}(\xi)=2 q_{0} \sqrt{\pi}\left\{1+\frac{4}{2 \pi}\left[\frac{1}{4} \ln \frac{(1-b)(1-a)}{(1+a)(1-b)}+\frac{a+3 b-4 a b}{2(1-a)(1-b)}-\right.\right. \\
& \left.\left.\left(1 \frac{\overline{1-b}}{1-b}+1 \frac{\overline{1+a}}{1-a}\right) \frac{1 \sqrt{1-l^{2}}+\sqrt{1-a^{2}}}{b-a}\right]\right\}+O\left(\varepsilon^{2}|\ln \varepsilon|\right) \\
& K_{b}(v)=2 q_{0} \sqrt{\varepsilon}\left\{\frac{1-a b+\sqrt{\left.\Pi-a^{2}, i\right]-b^{2}}}{(b-a) \sqrt{1-b^{2}}}\right\}+O\left(\varepsilon^{9}|\ln \varepsilon|\right)
\end{aligned}
$$

Finally, we formulate one more result. We consider the crack arrangement shown in Fig. 3 in the case when the cracks have the same unit length while the dimensions of the rectangle $\Pi_{\varepsilon} \quad$ between the cracks are $l \times \varepsilon ; l \in(0,1)$. The relationship

$$
\begin{aligned}
& K(\varepsilon, l)=2 q_{0} \sqrt{\varepsilon} x(l)+O\left(\xi^{\prime \prime}|\ln \varepsilon|\right) \\
& x(l)=\frac{2 \sqrt{1-l}}{l} \div \frac{l}{2 \sqrt{1-l}}=\frac{4-4 l+l^{2}}{2 l \sqrt{1-l}}
\end{aligned}
$$

holds for the intensity factor $K(\varepsilon, l)$ at the right tip of the crack $M_{\varepsilon}$ for problem (1.1), (7.18).

As $l \rightarrow 0$ and $l \rightarrow 1$ the quantity $x(l)$ tends to $\infty$; for values of $l$ and $1-l$ close to $\varepsilon$, the formula for $K(\varepsilon, l)$ loses accuracy because of the breakdown of the assumption about the smallness of $\varepsilon$ (see Sect.1). A minimum of the function $x$ (Fig.4) and the stress intensity factor are achieved at the point $l_{*}=2(\sqrt{2}-1)$.

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